

FIG. 1

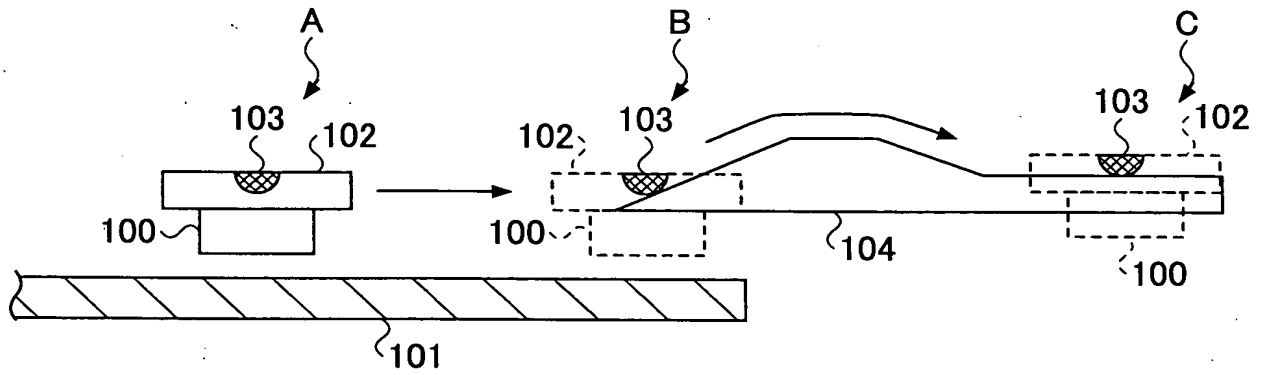


FIG.3

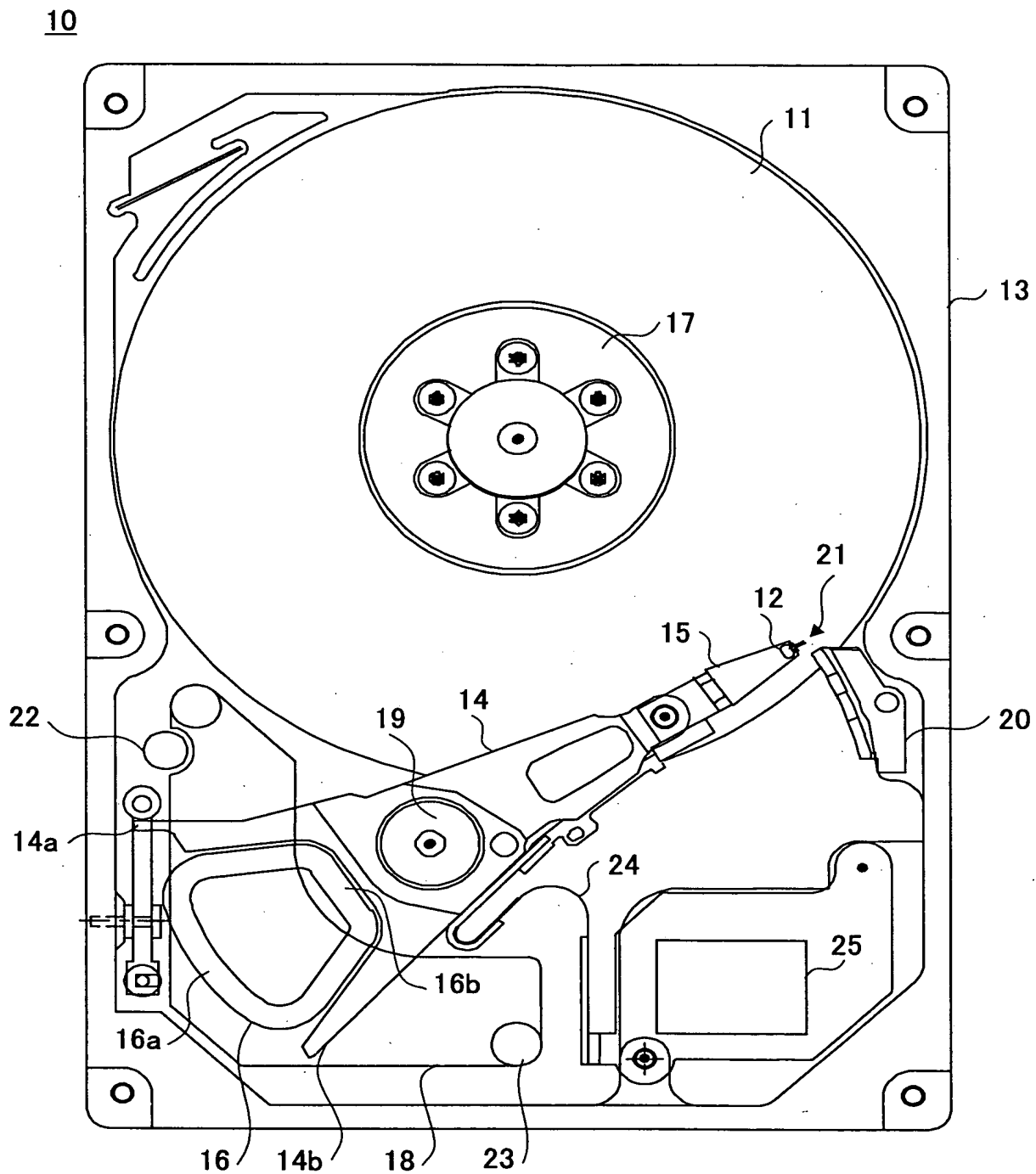


FIG.4

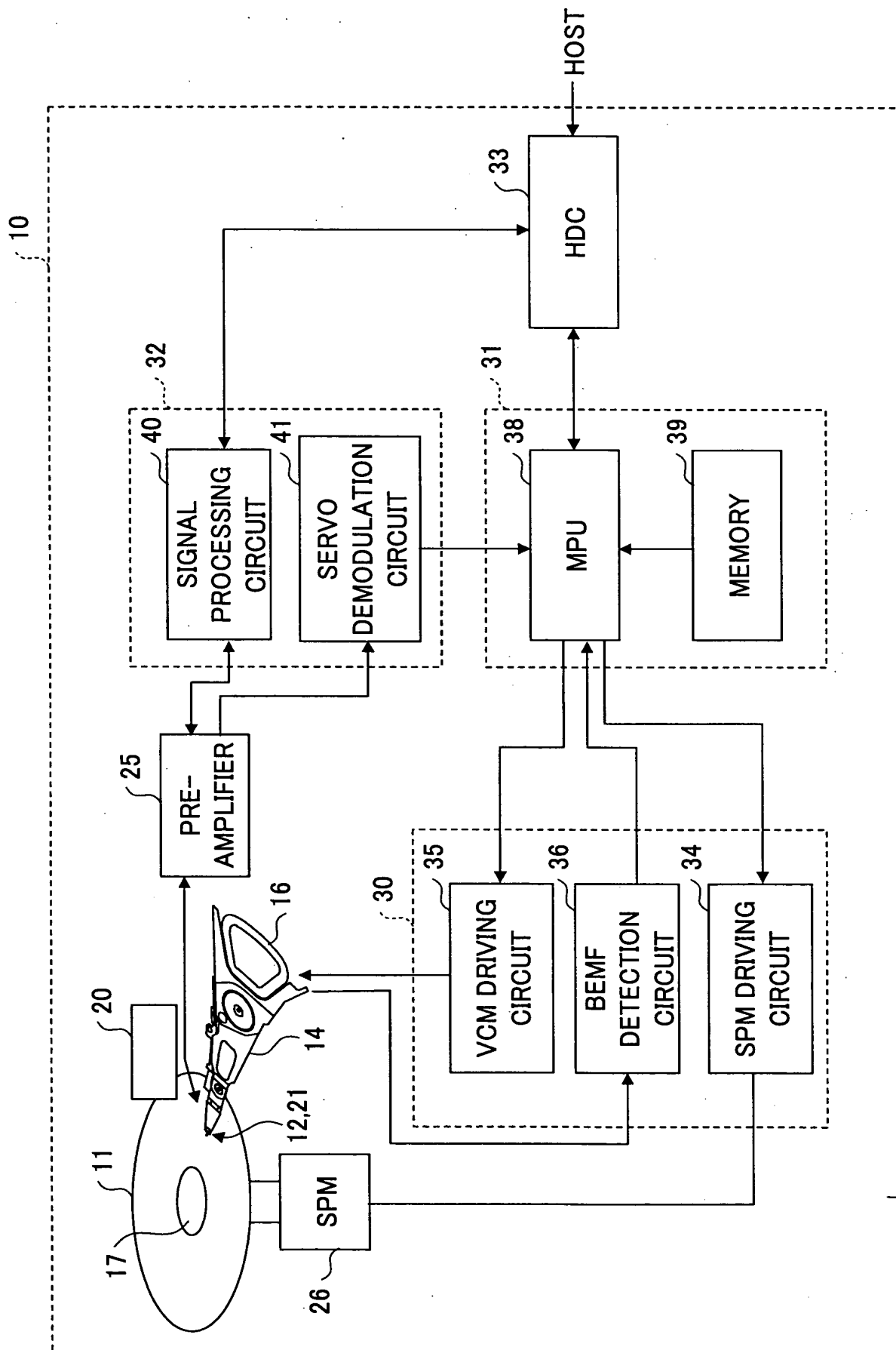


FIG.5

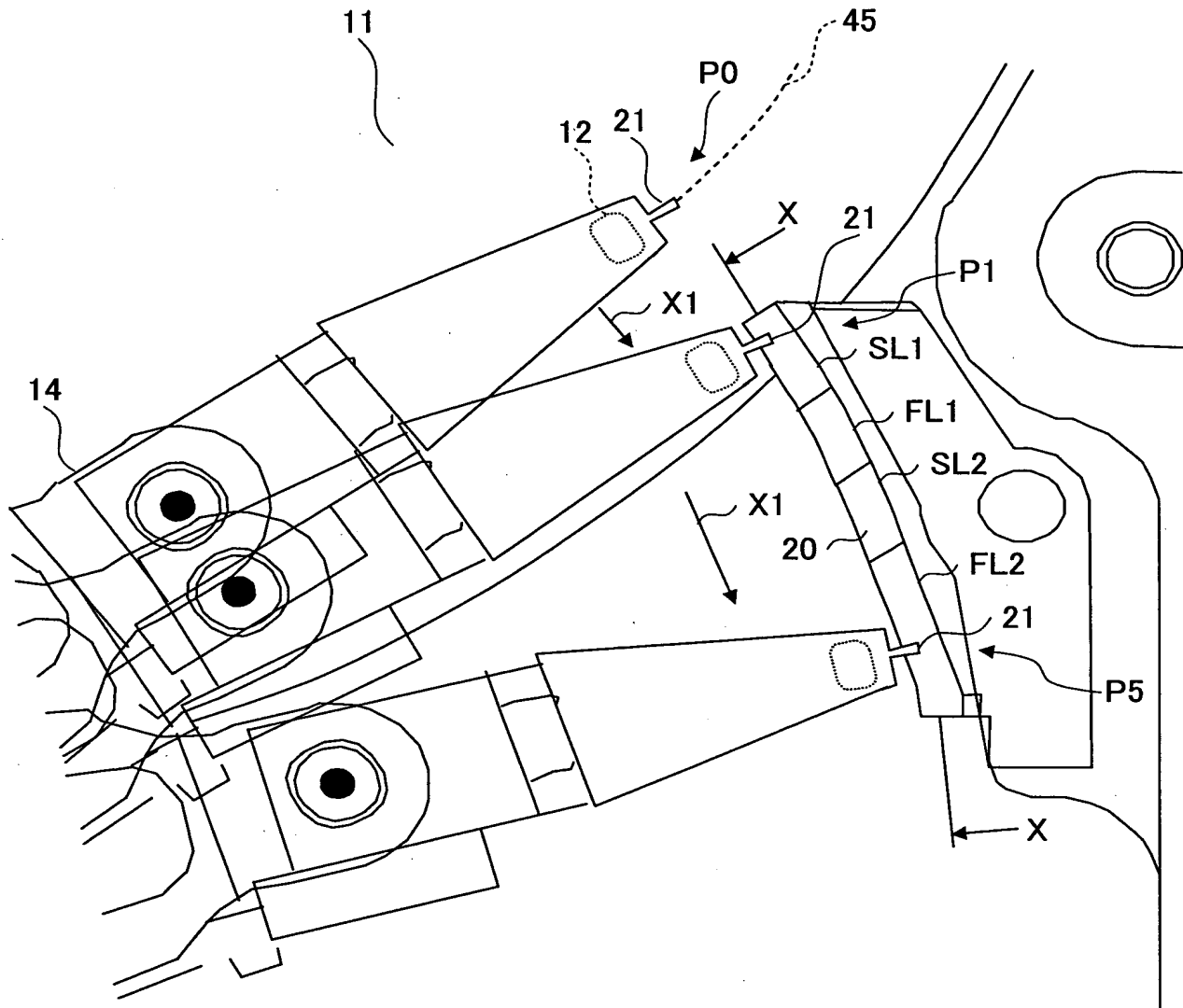


FIG.6

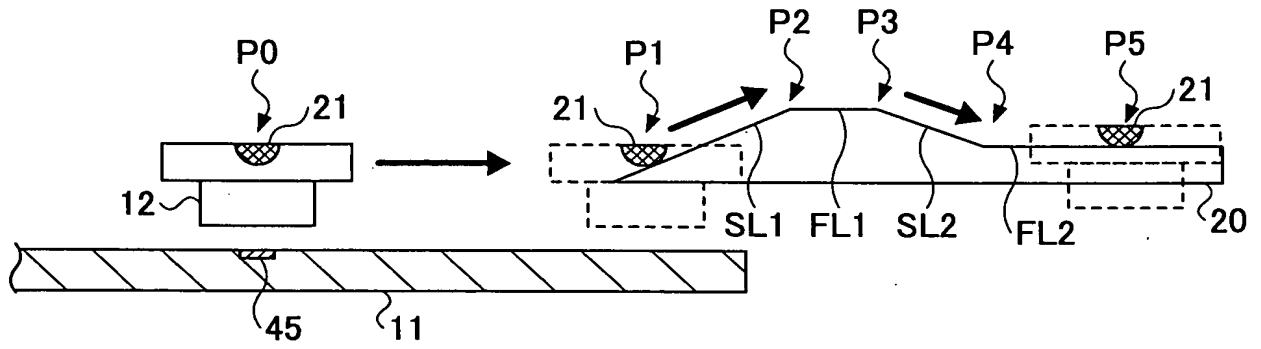


FIG. 7

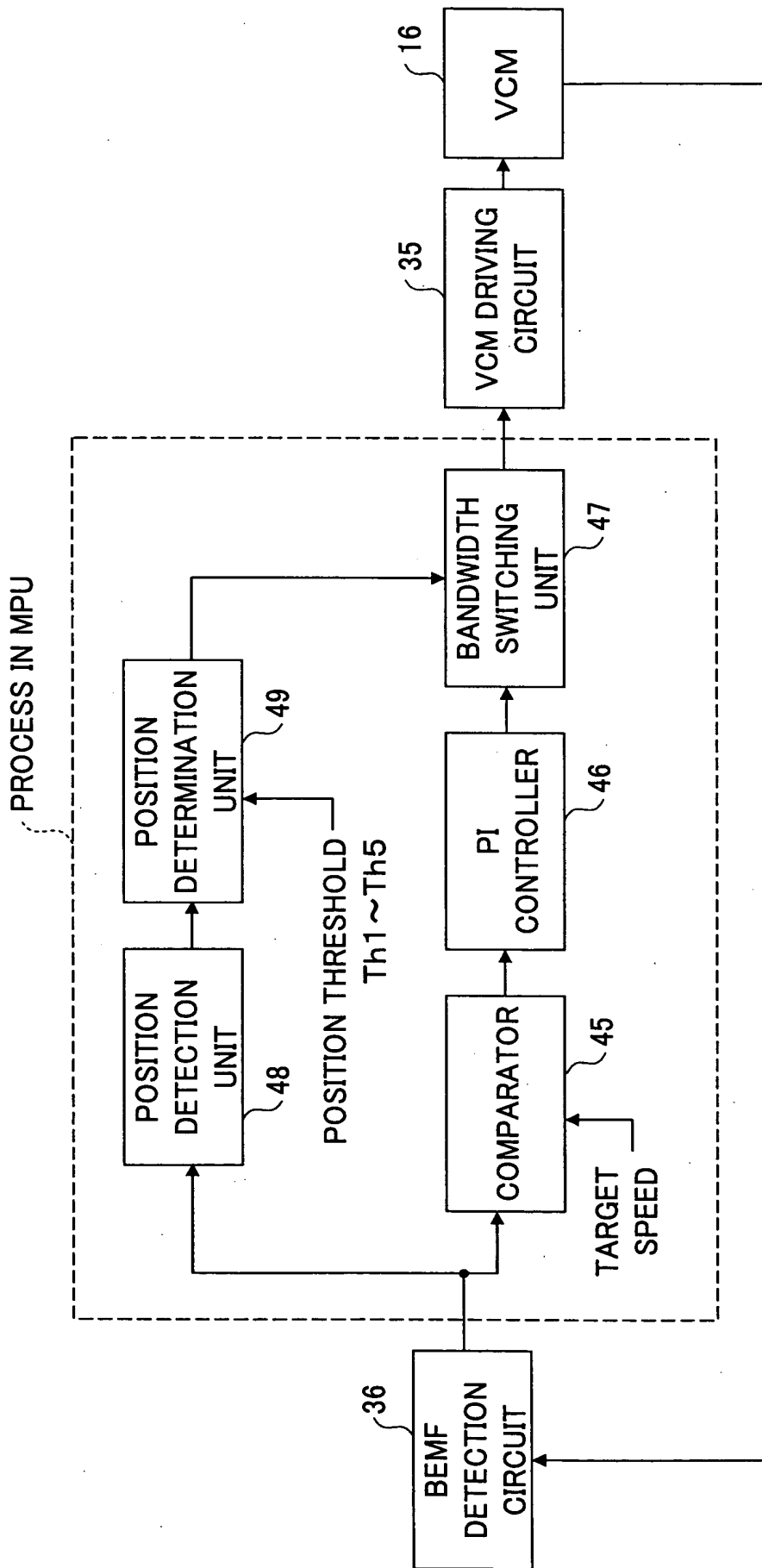
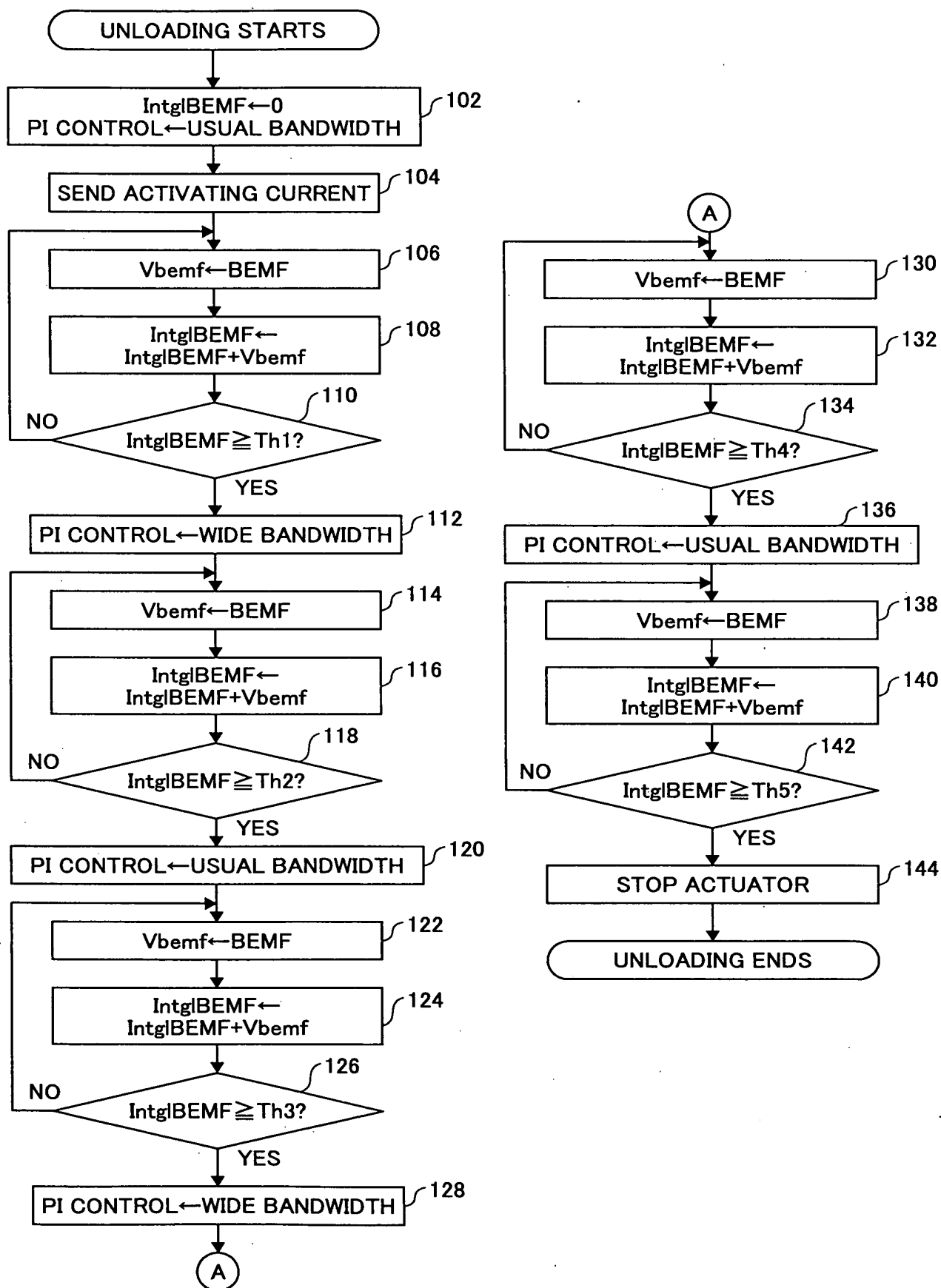


FIG.8



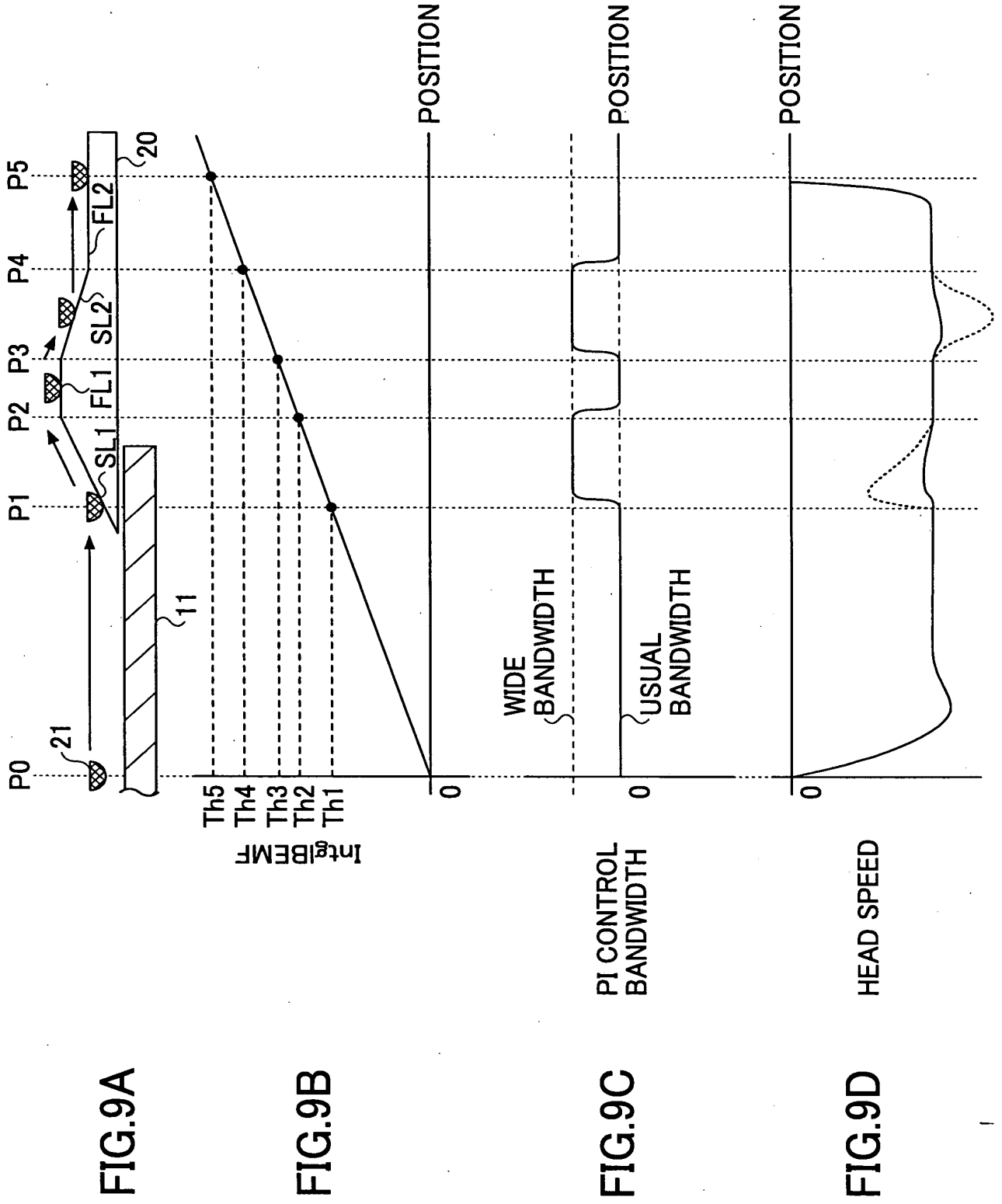
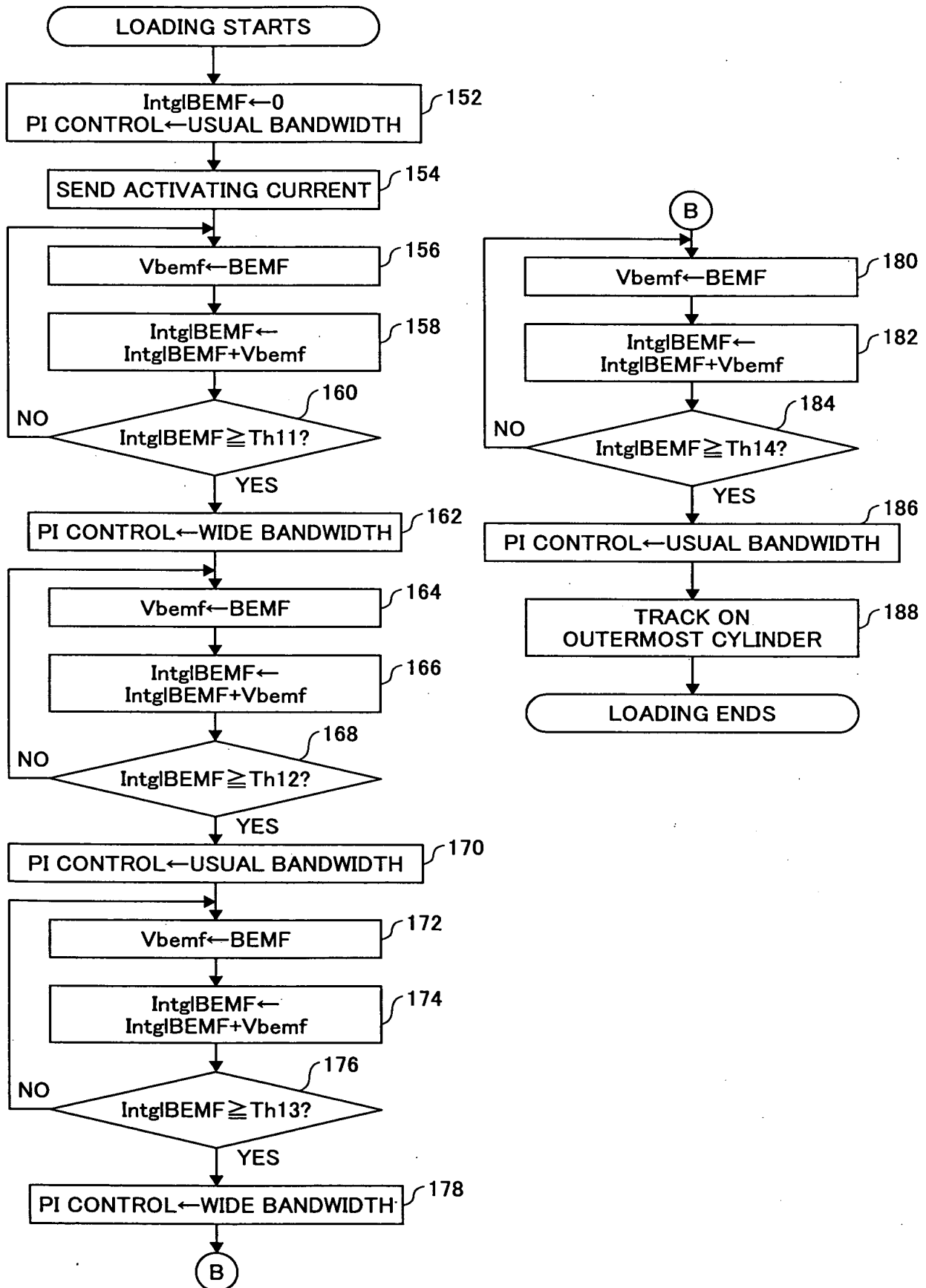
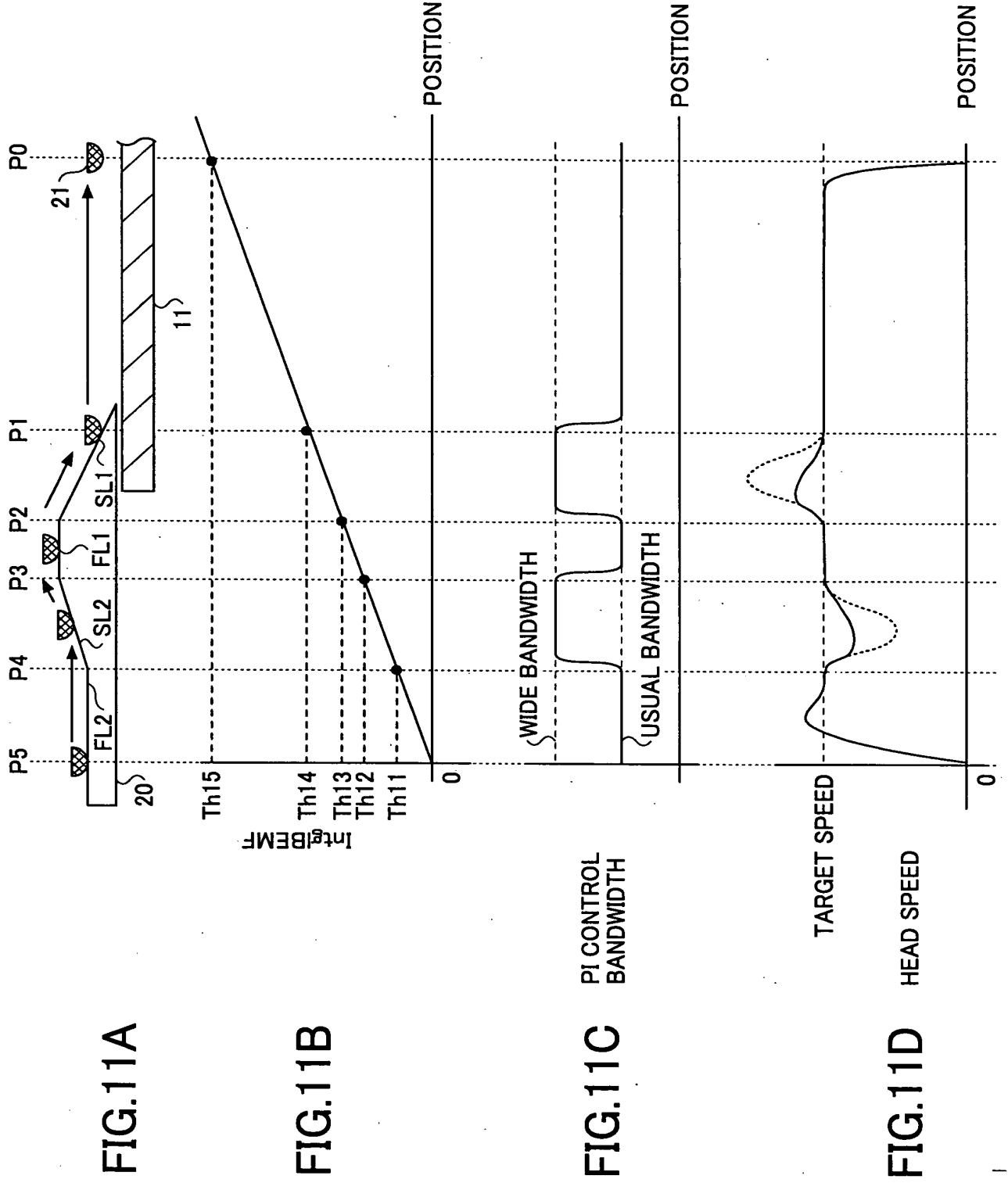


FIG.10





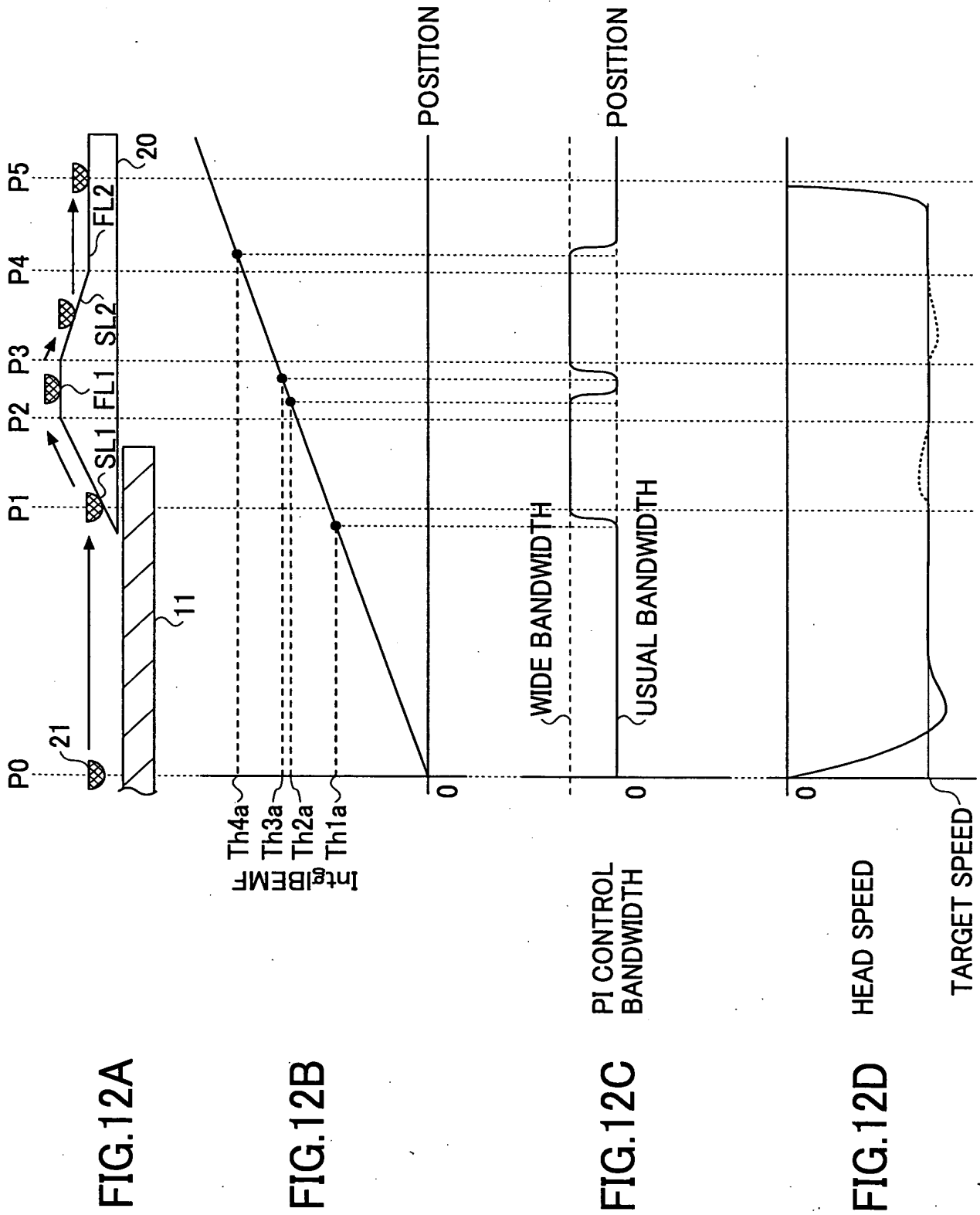


FIG.13

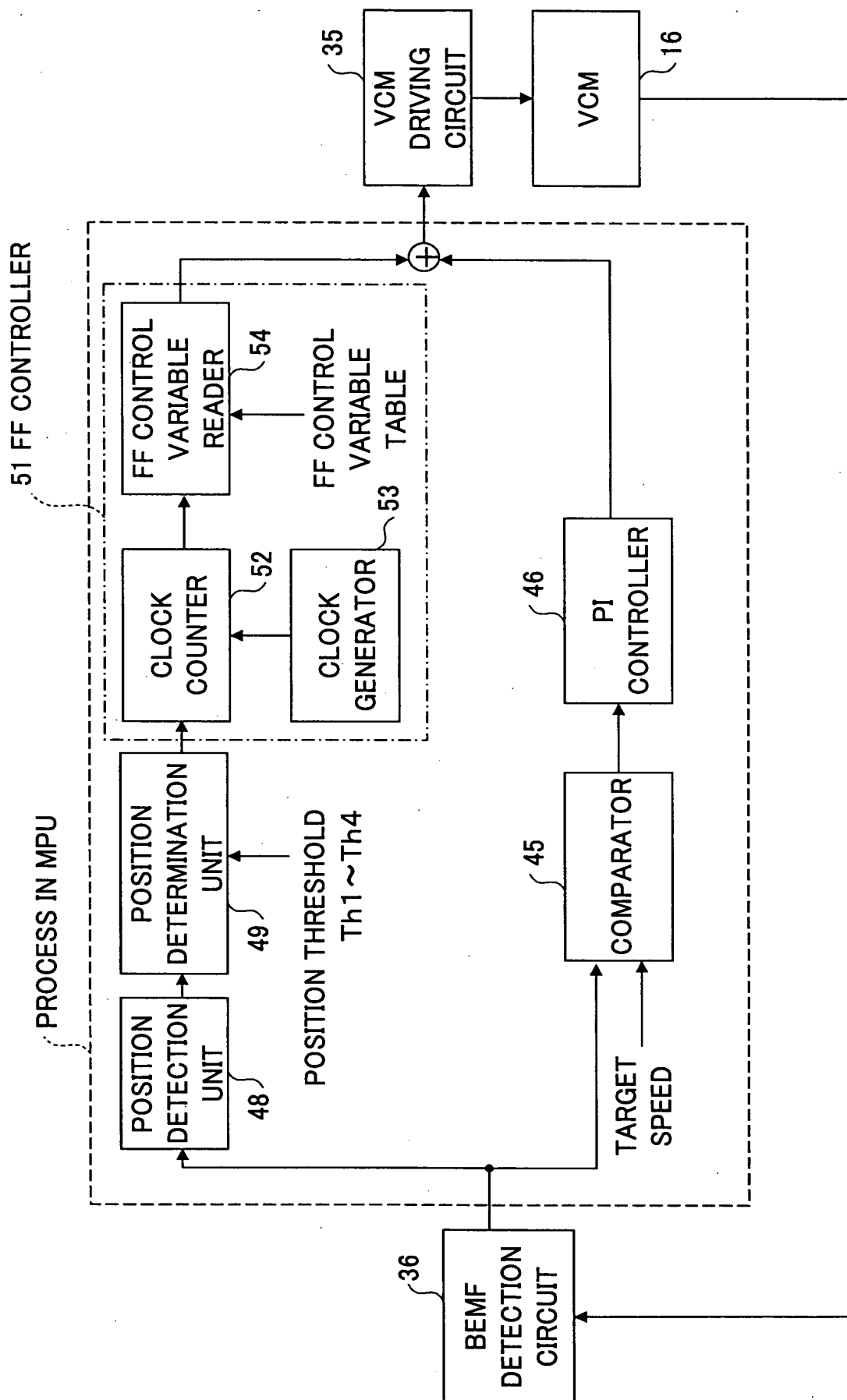


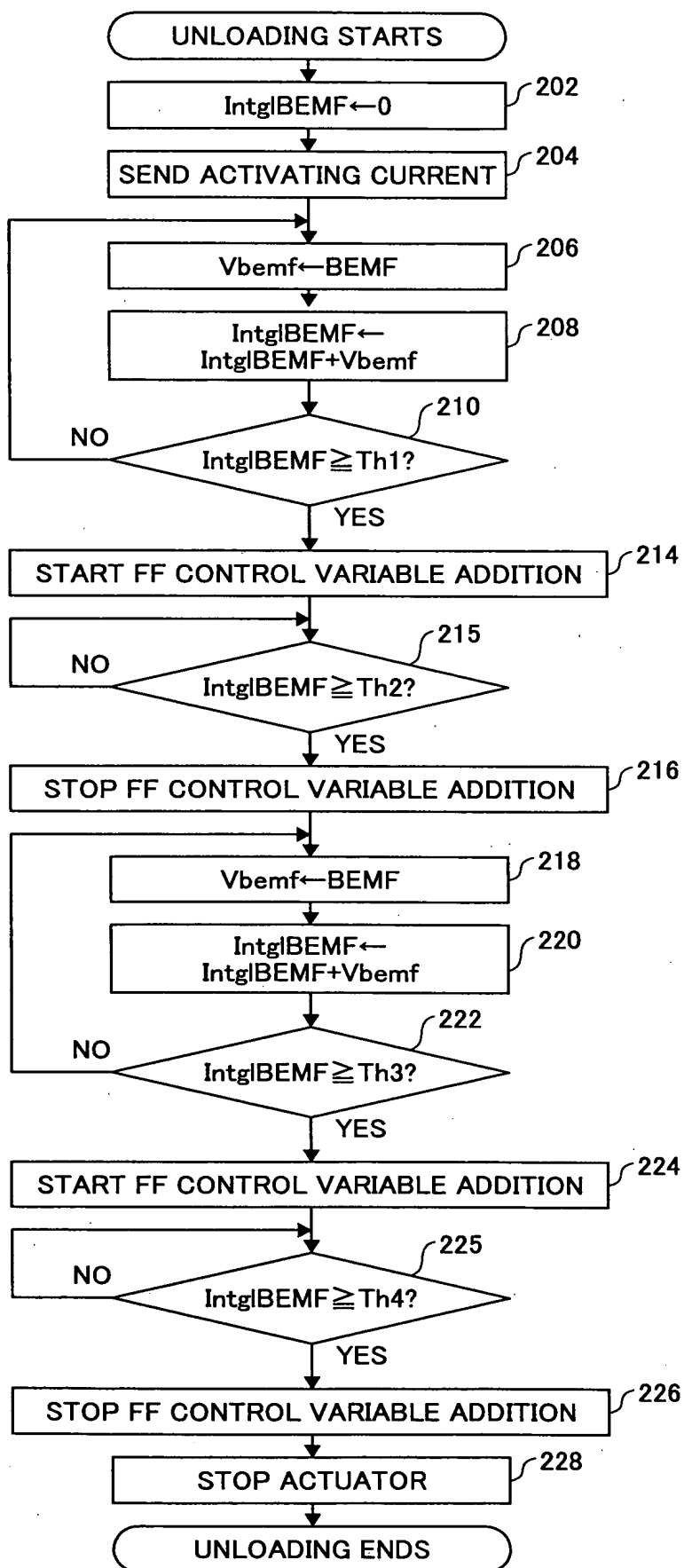
FIG.14A

TIME	FF CONTROL VARIABLE
0	-1
1	-3
2	-6
:	:
m-2	-6
m-1	-3
m	-1

FIG.14B

TIME	FF CONTROL VARIABLE
0	1
1	3
2	6
:	:
n-2	6
n-1	3
n	1

FIG.15



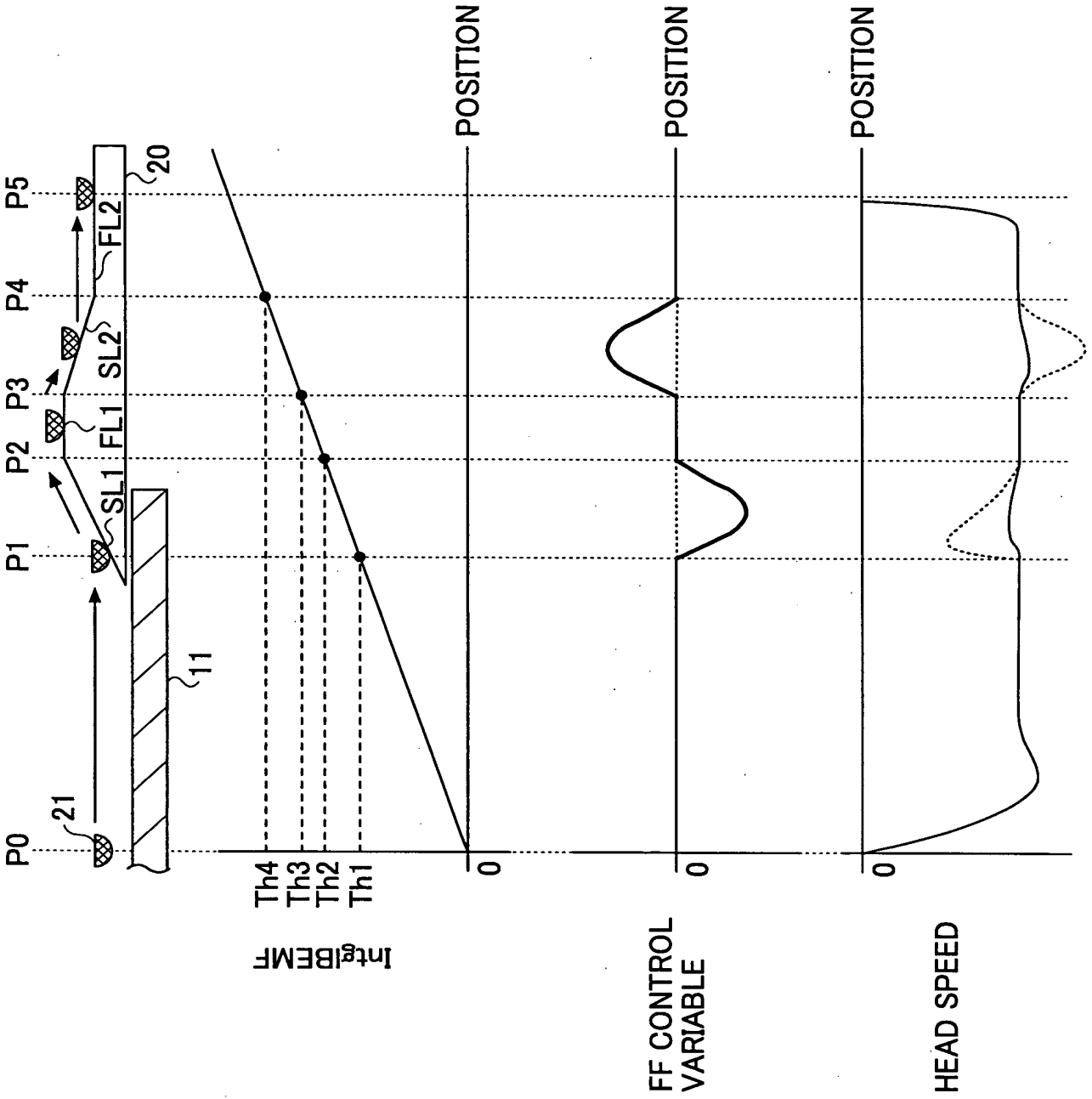


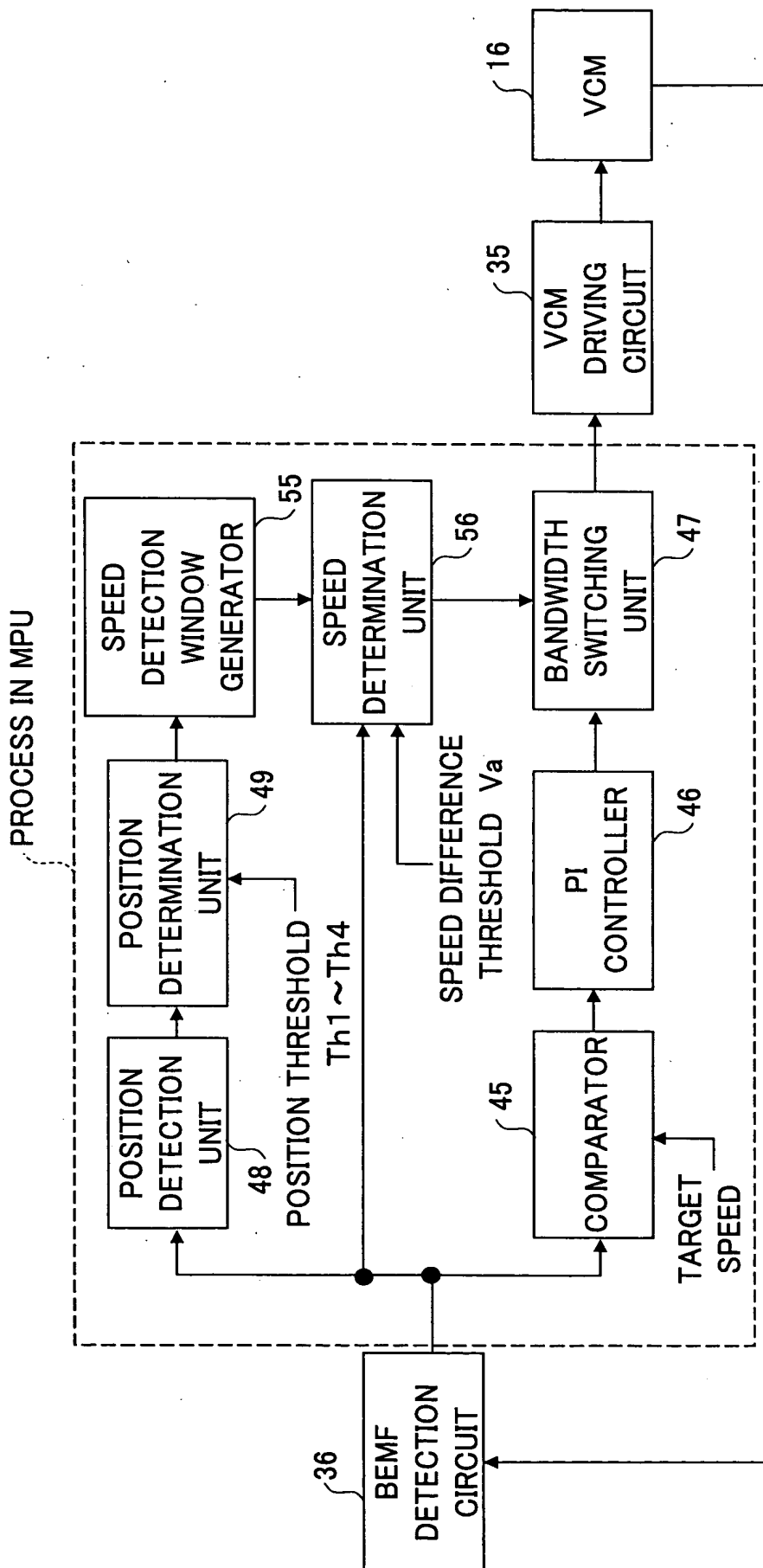
FIG. 16A

FIG. 16B

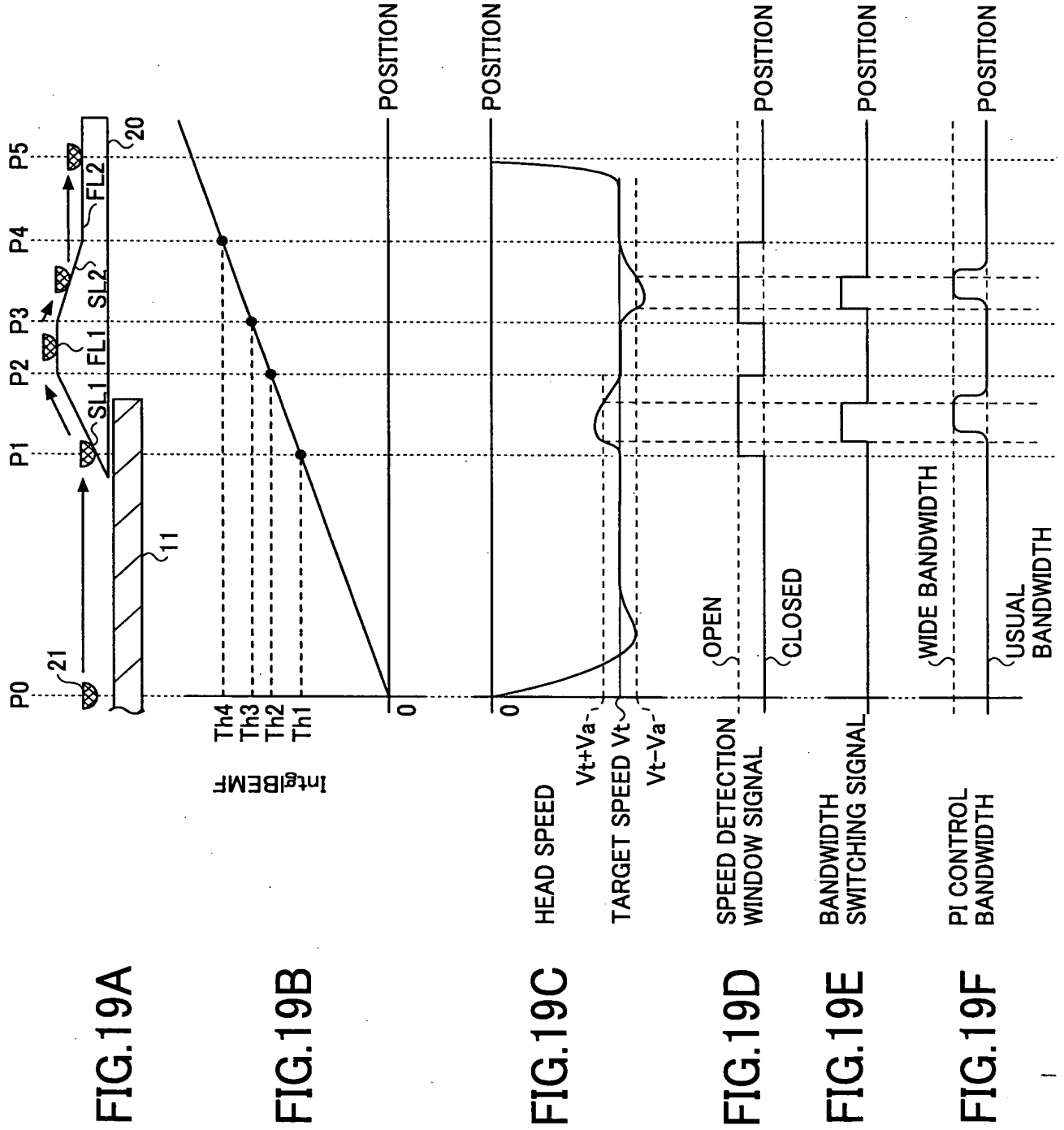
FIG. 16C

FIG. 16D

FIG.17







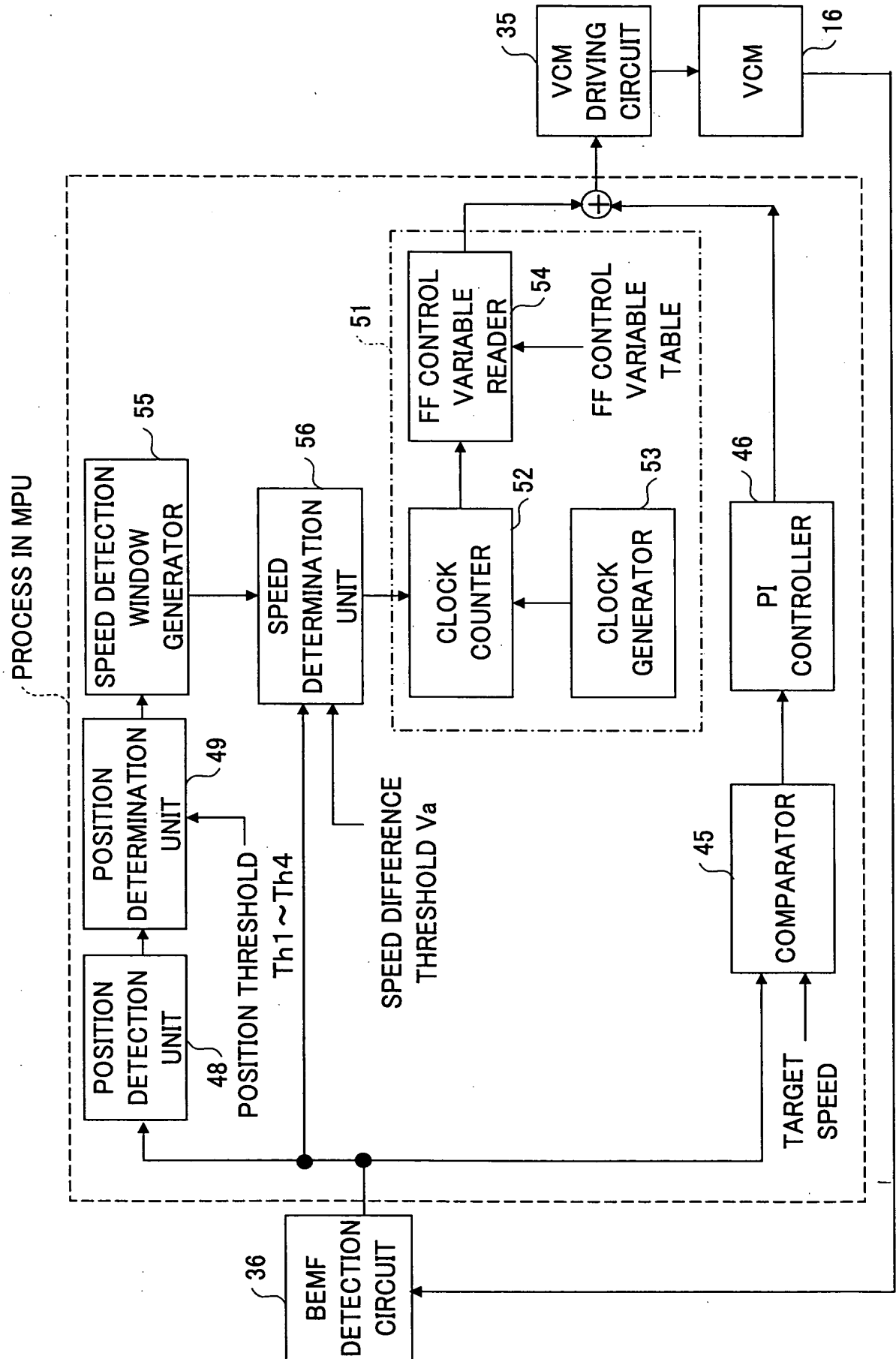
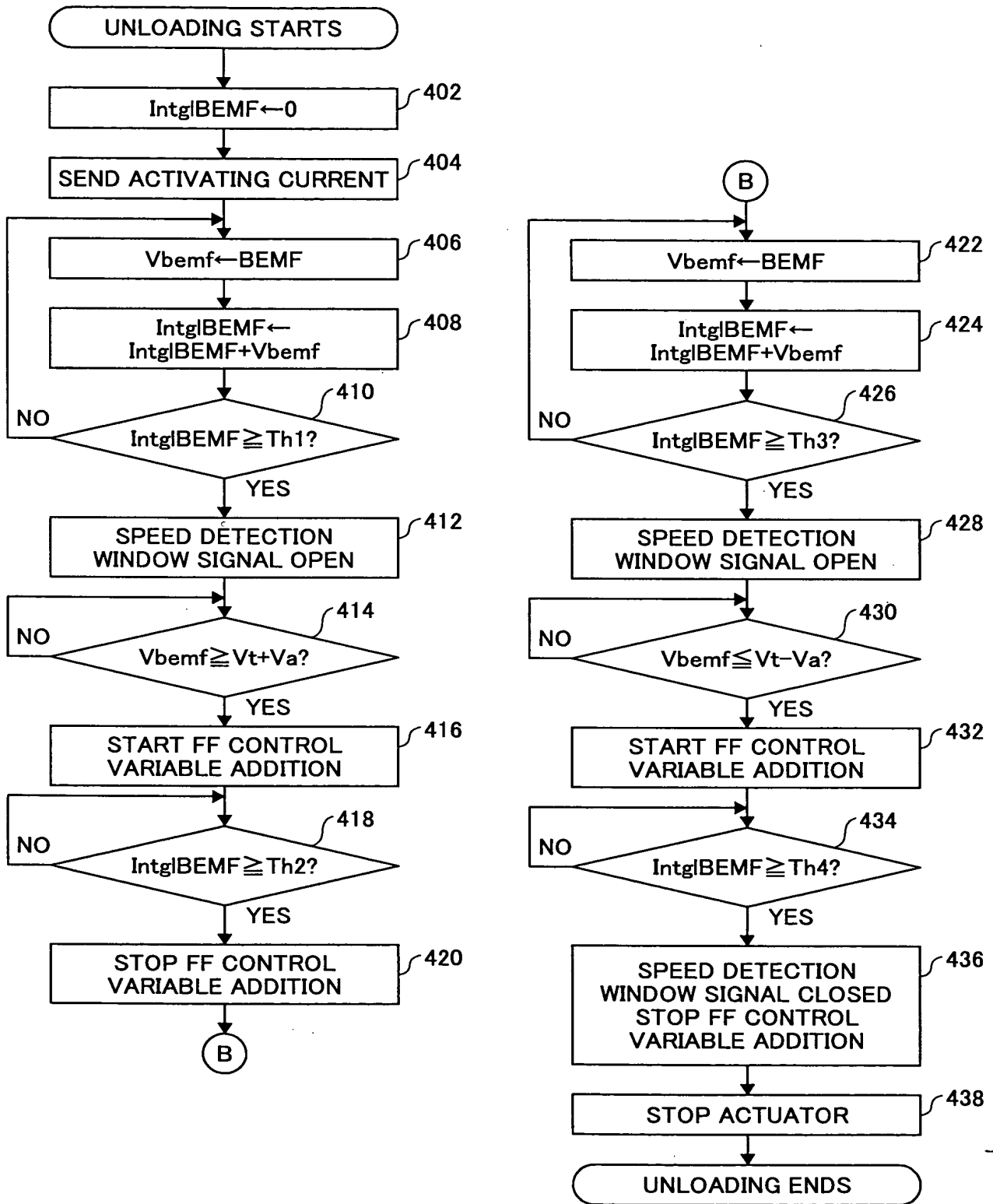


FIG.21



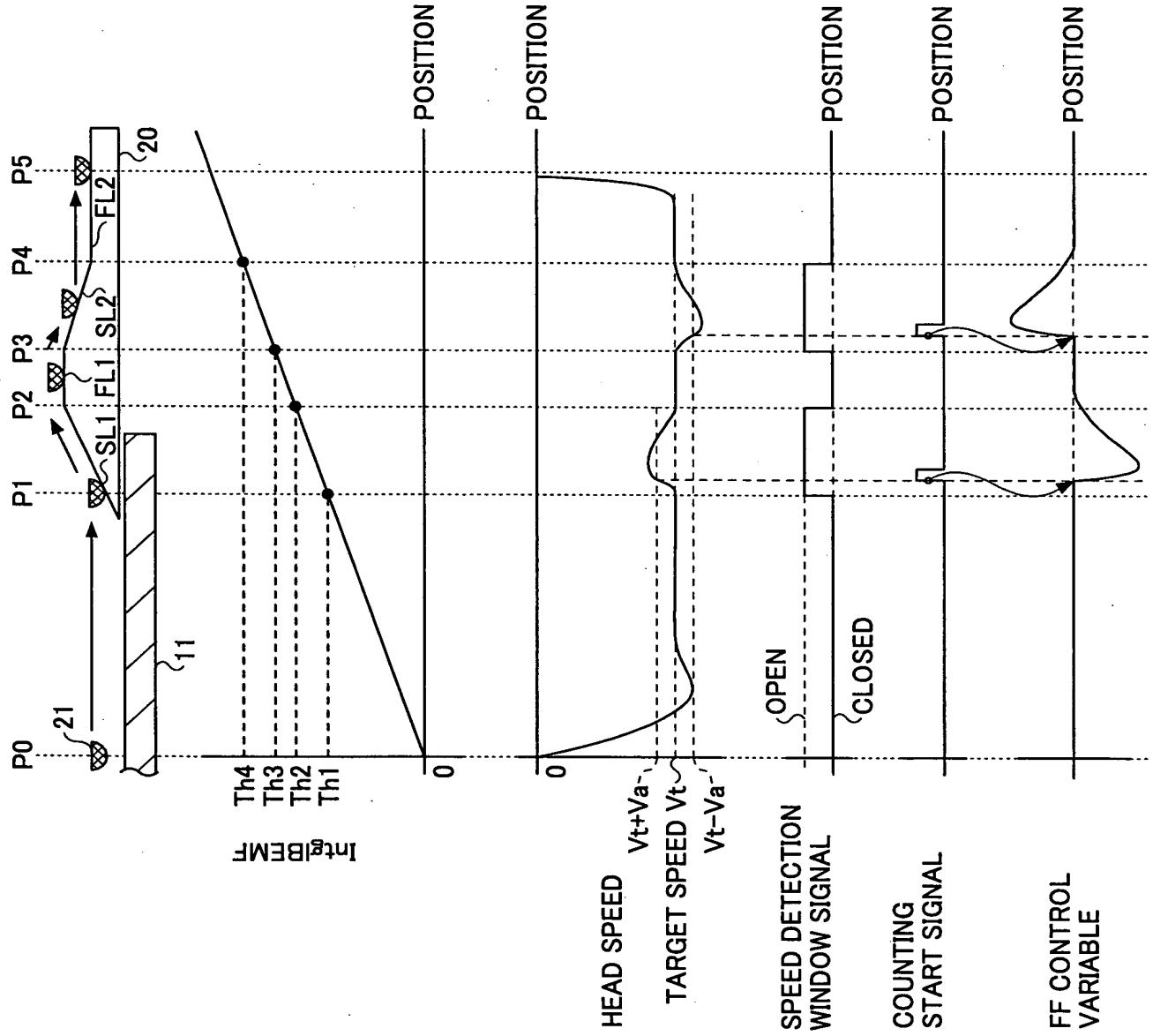


FIG. 22A

FIG. 22B

FIG. 22C

FIG. 22D

FIG. 22E

FIG. 22F

FIG.23

